Motorcycle multibody model validation for Human-in-the-Loop simulation

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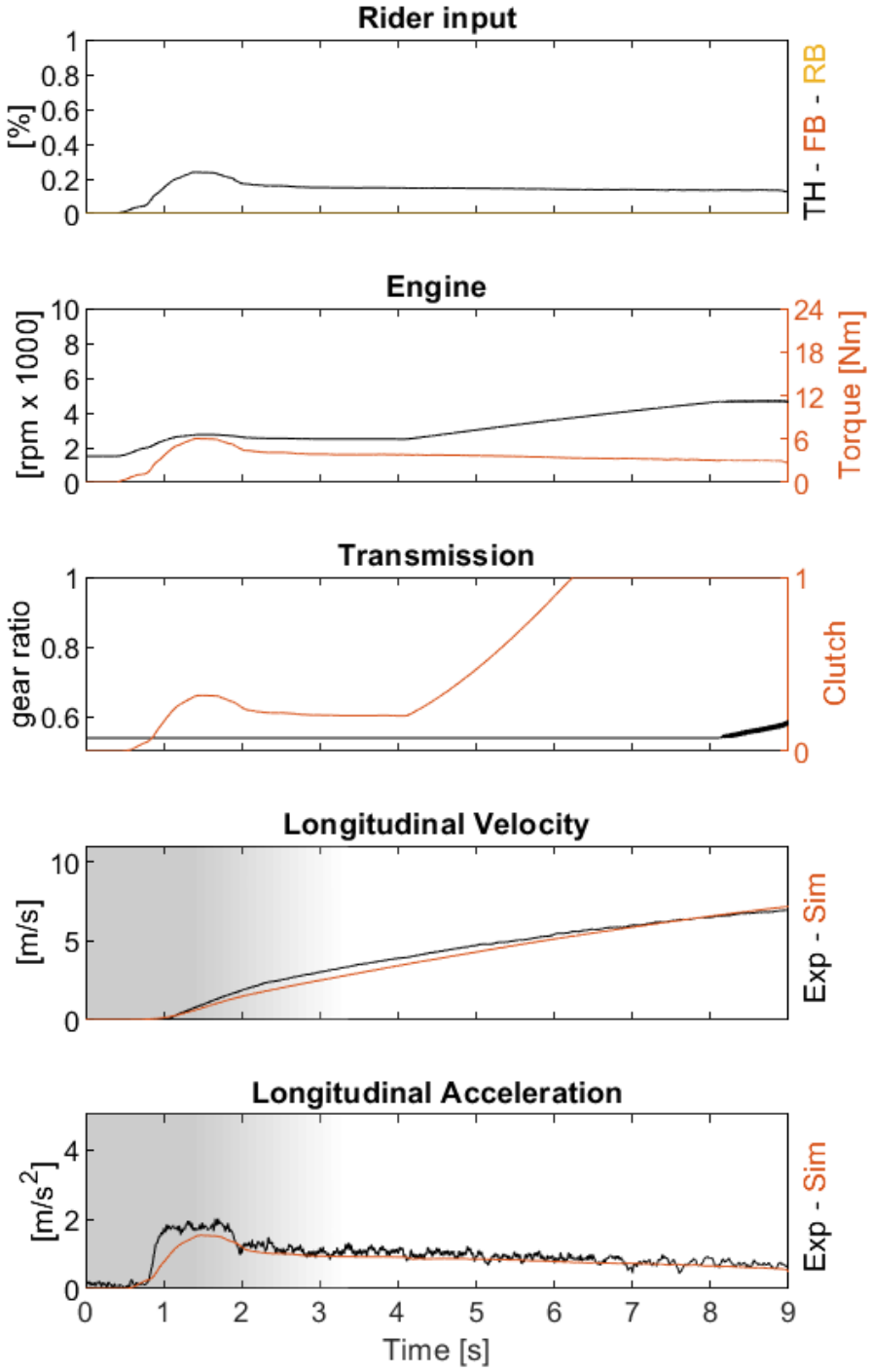

Figure 1: Maneuver A30. Comparison between model simulation and measurements on a real motorcycle. TH : throttle, FB : front brake, RB : rear brake.

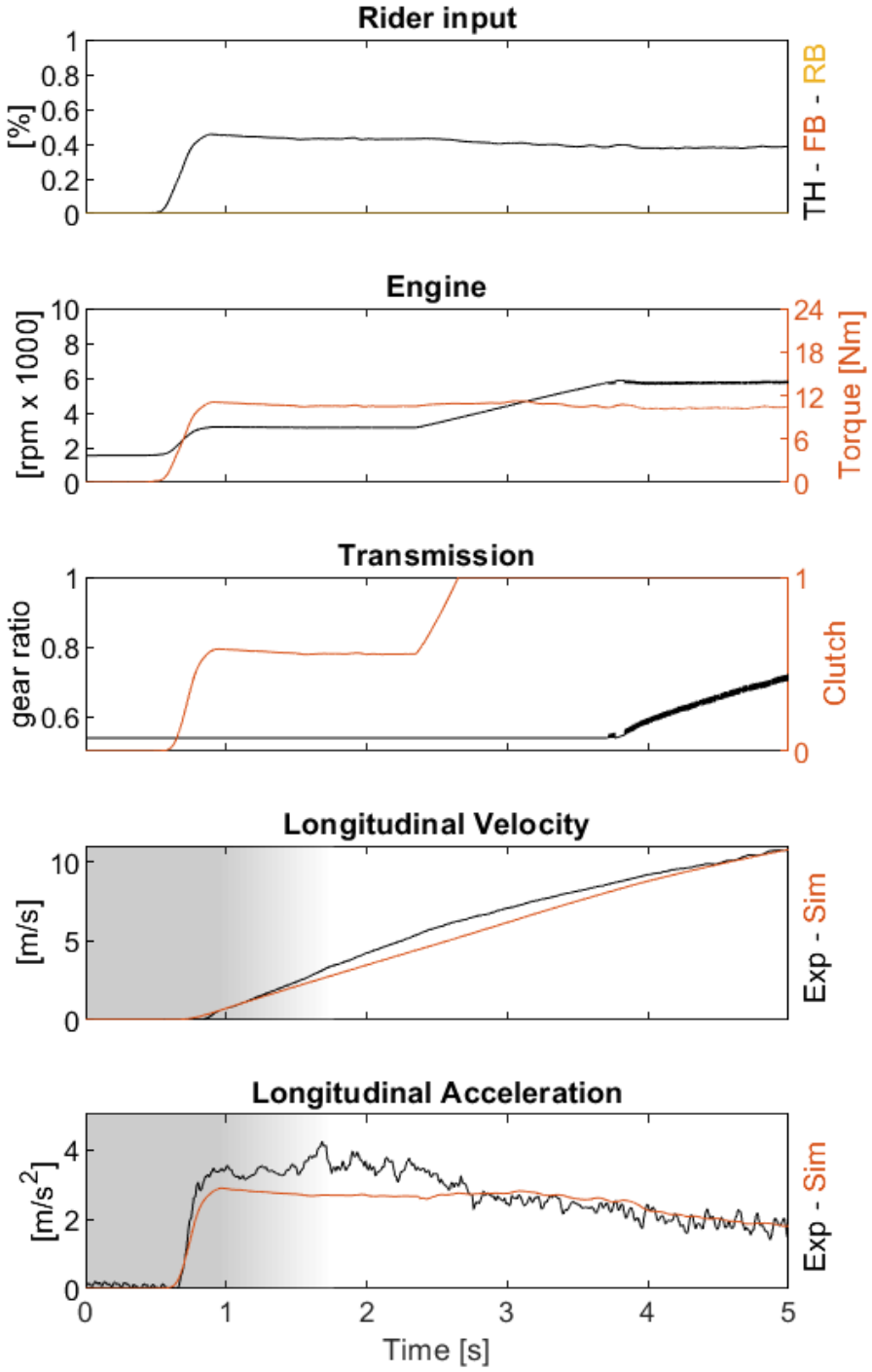

Figure 2: Maneuver A50. Comparison between model simulation and measurements on a real motorcycle. TH : throttle, FB : front brake, RB : rear brake.

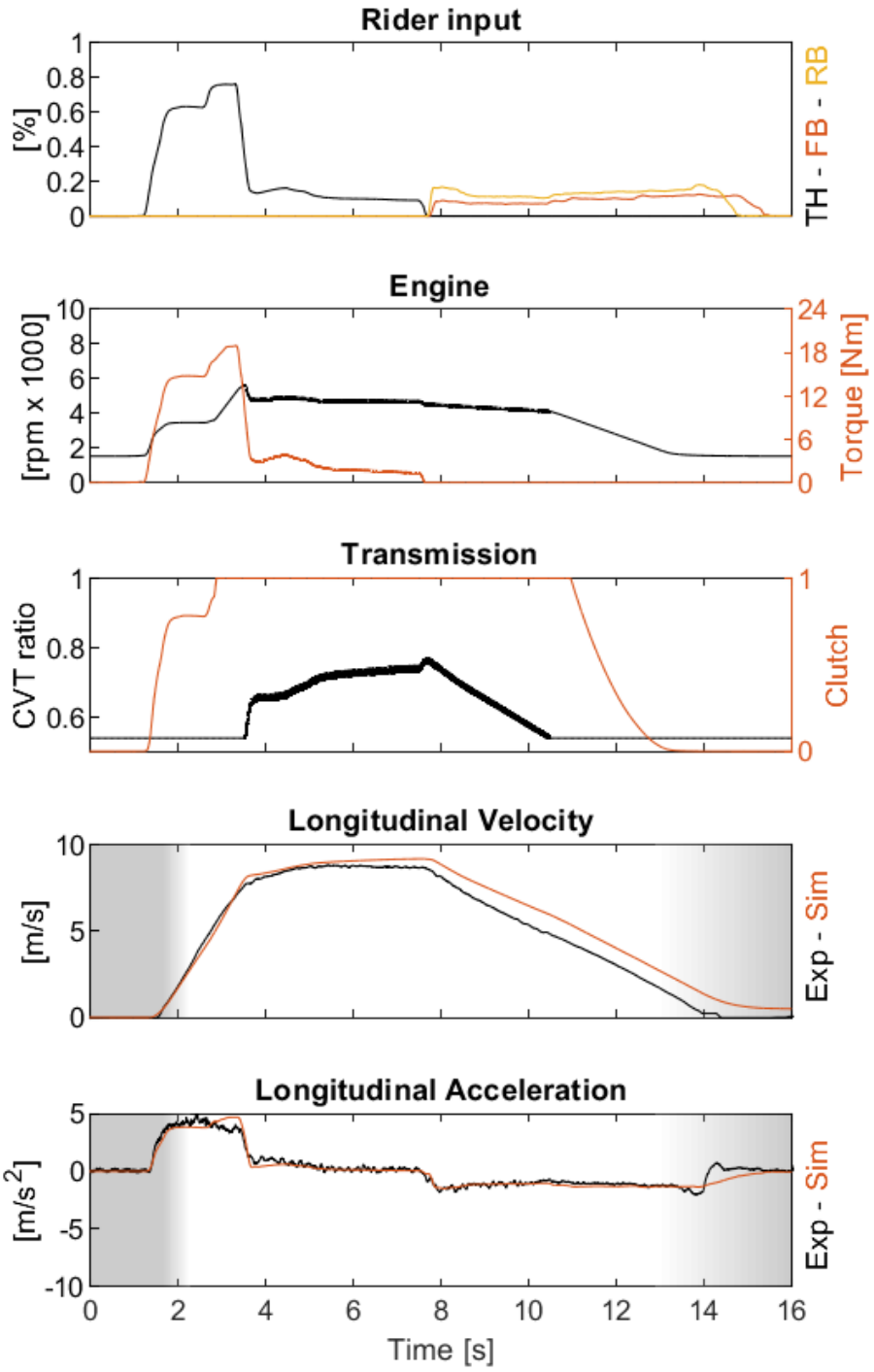

Figure 3: Maneuver B25. Comparison between model simulation and measurements on a real motorcycle. TH : throttle, FB : front brake, RB : rear brake.

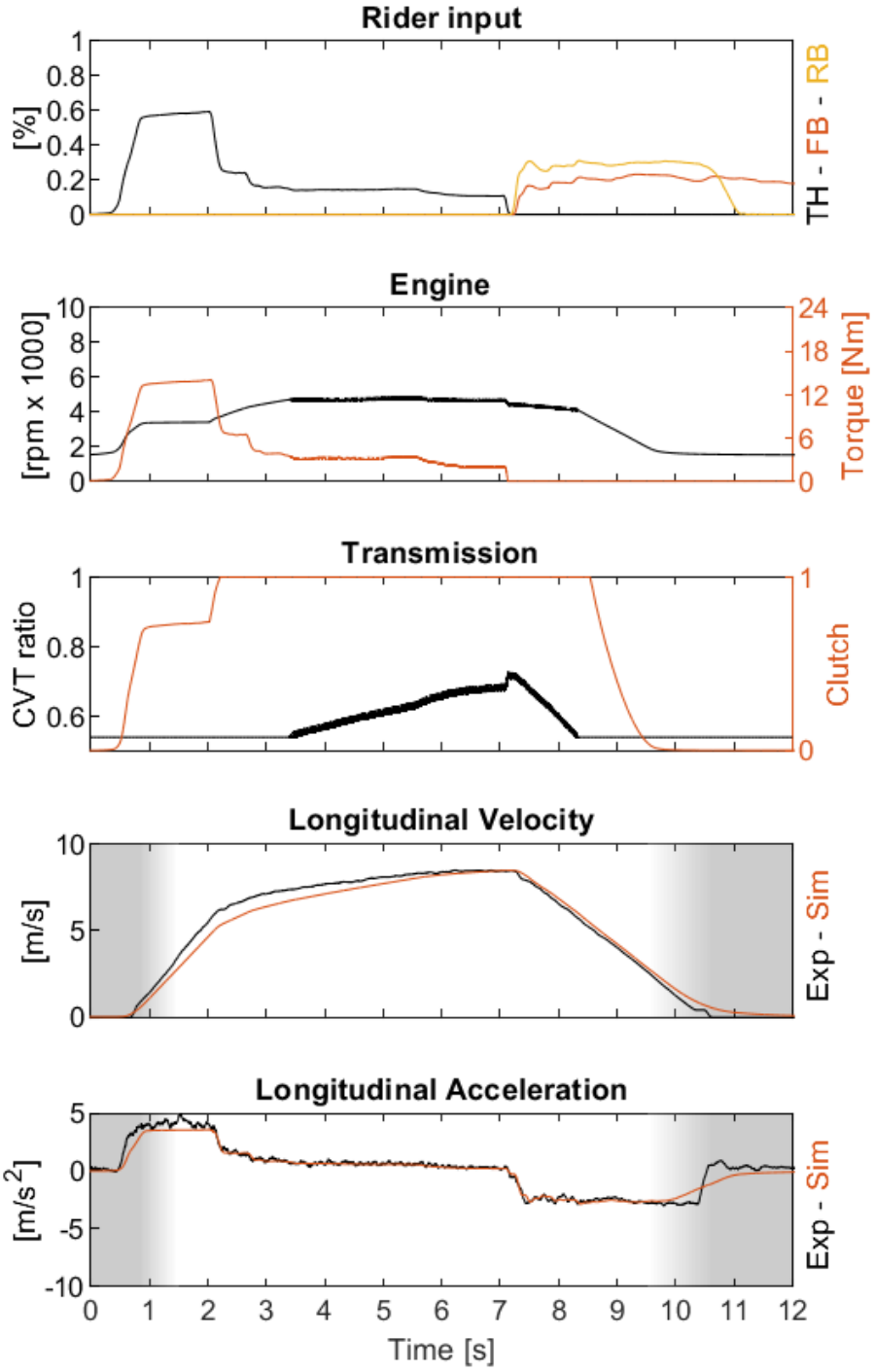

Figure 4: Maneuver B12. Comparison between model simulation and measurements on a real motorcycle. TH : throttle, FB : front brake, RB : rear brake.

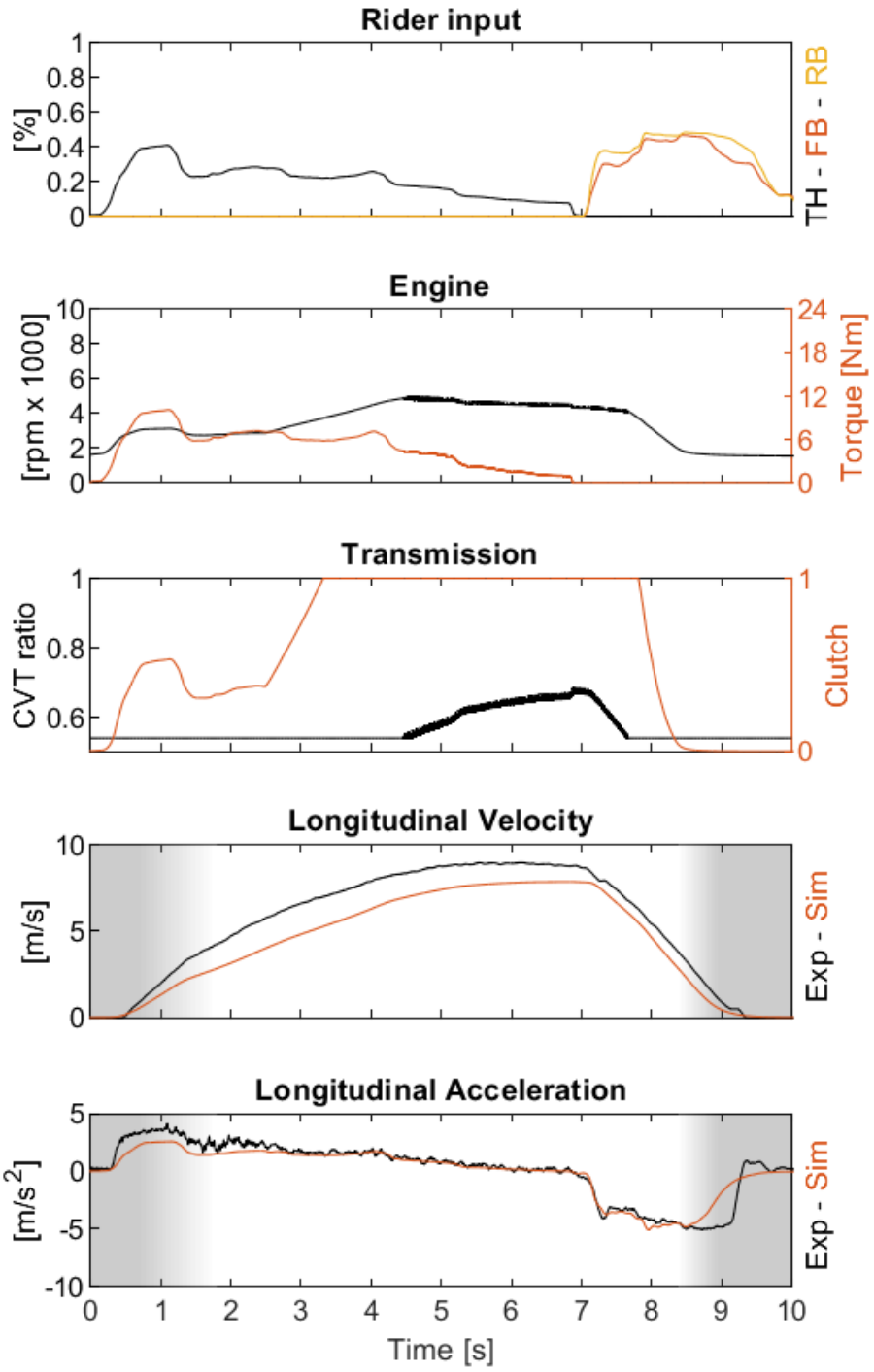

Figure 5: Maneuver B7.5. Comparison between model simulation and measurements on a real motorcycle. TH : throttle, FB : front brake, RB : rear brake.

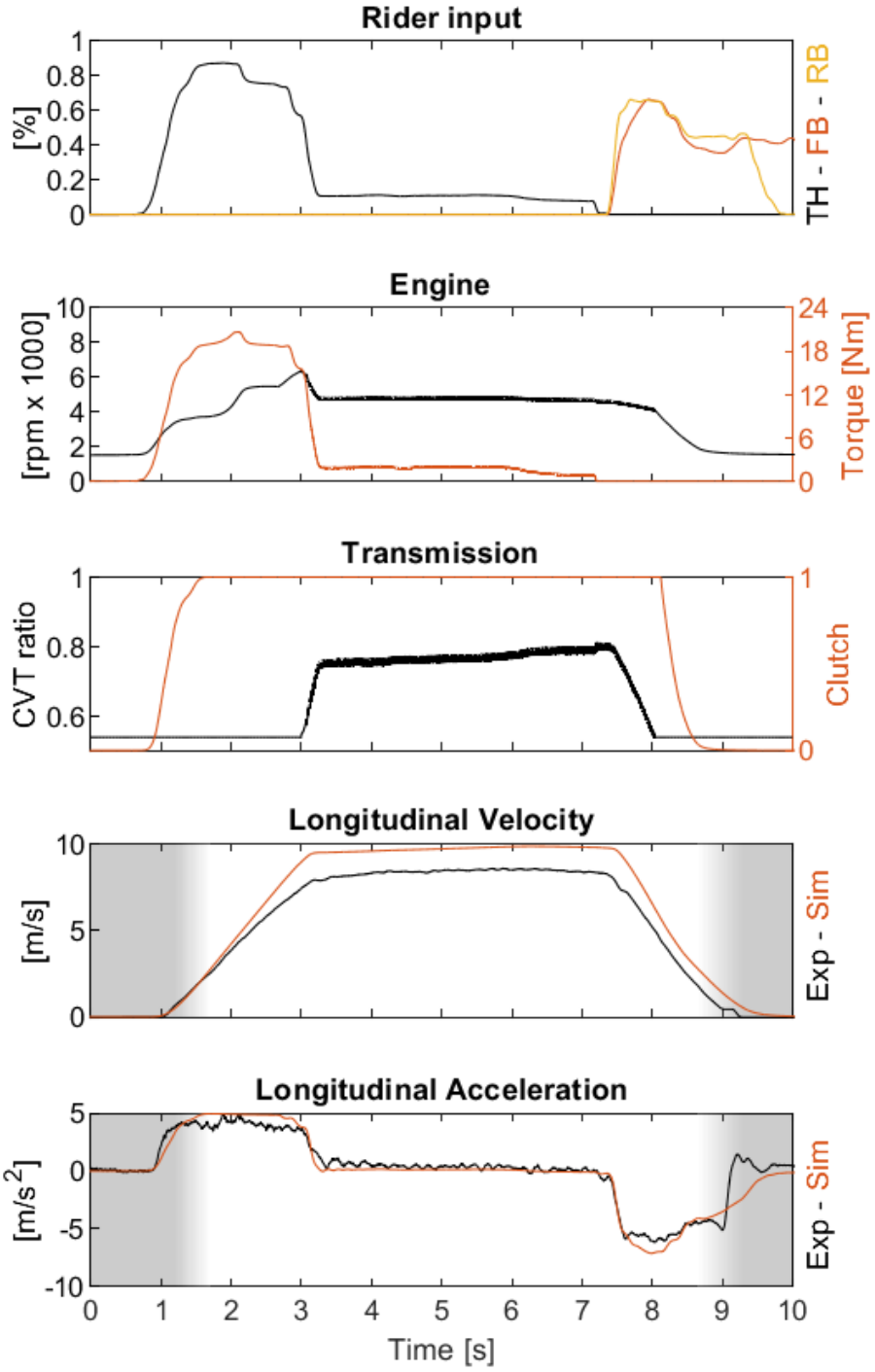

Figure 6: Maneuver B5.5. Comparison between model simulation and measurements on a real motorcycle. TH : throttle, FB : front brake, RB : rear brake.

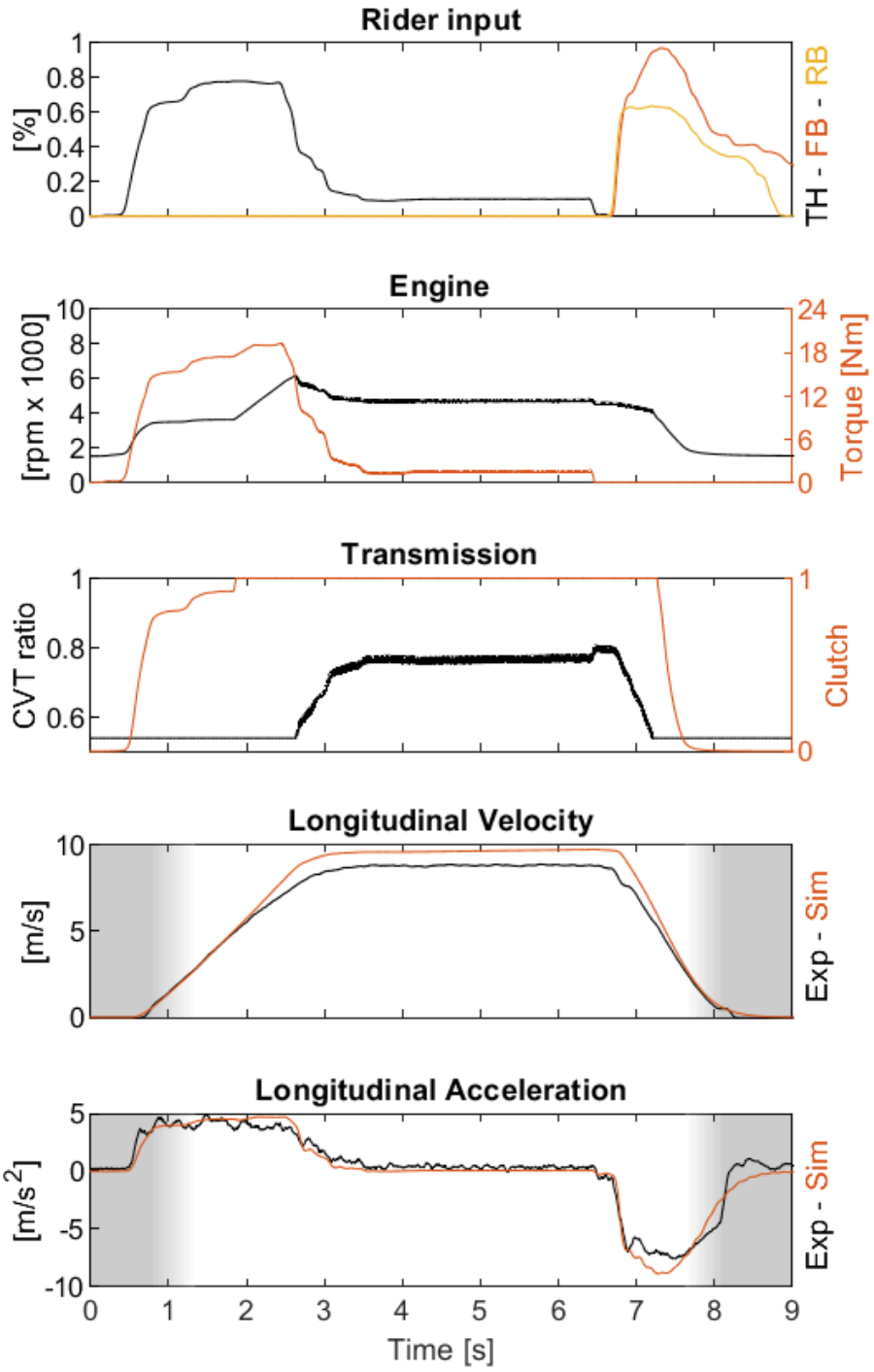

Figure 7: Maneuver B4.5. Comparison between model simulation and measurements on a real motorcycle. TH : throttle, FB : front brake, RB : rear brake.

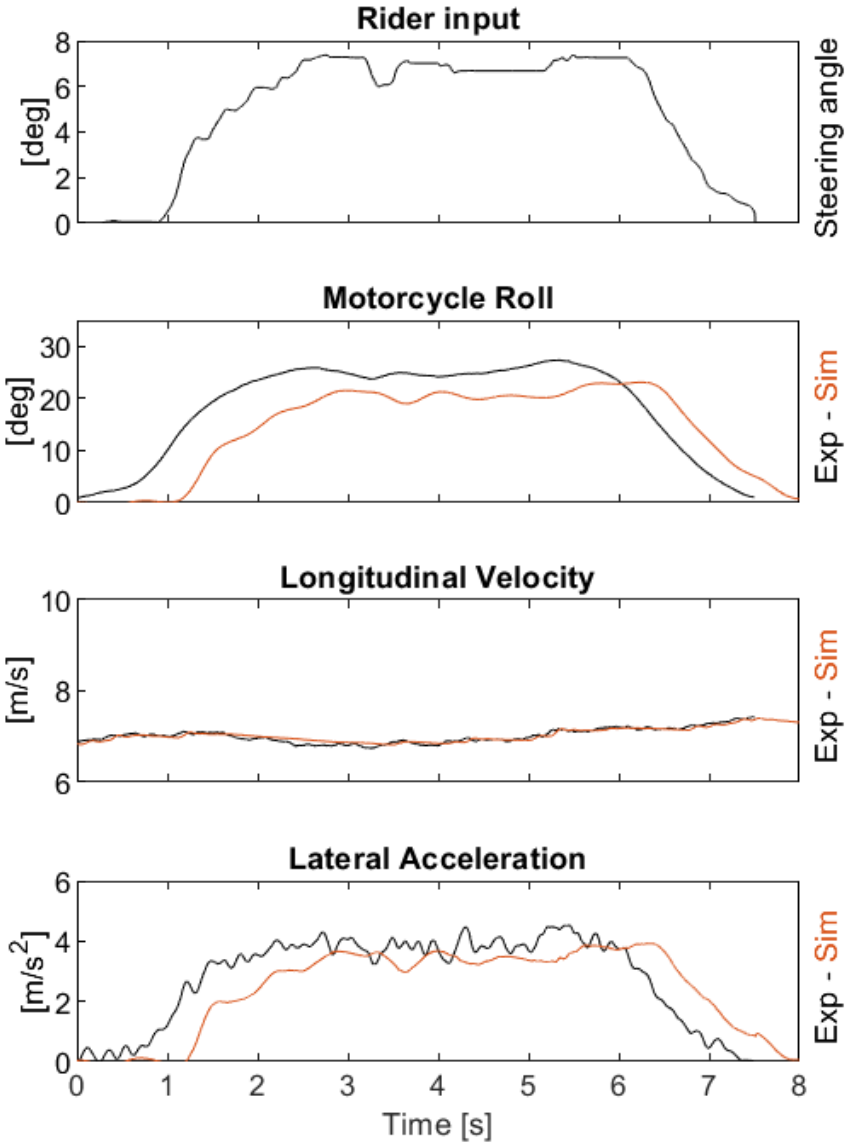

Figure 8: Maneuver U25. Comparison between model simulation and measurements on a real motorcycle.